

## PATENT ABSTRACTS OF JAPAN

(11)Publication number : 05-282696

(43)Date of publication of application : 29.10.1993

(51)Int.Cl.

**G11B 7/125**

**G11B 7/00**

G11B 19/02

(21)Application number : 04-076913

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(22)Date of filing : 31.03.1992

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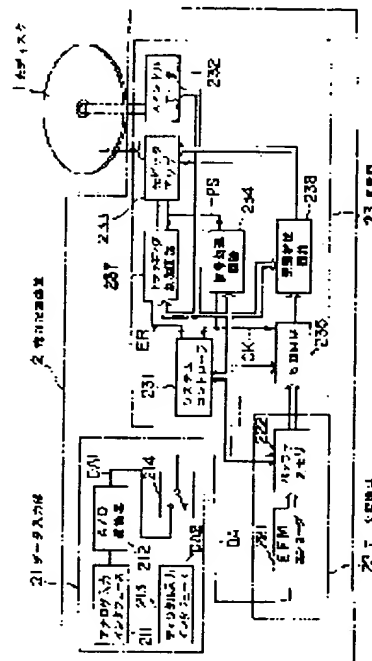
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## (54) METHOD FOR OPTICAL DISK INFORMATION RECORDING AND DEVICE THEREFOR

(57)Abstract:

**PURPOSE:** To provide the method for an optical disk information recording and device therefor which continues information recording even though a tracking is disengaged while information is being recorded.

CONSTITUTION: When a tracking is disengaged while information is recorded to an optical disk 1, tracking error signals are outputted from a tracking controlling circuit 237 to a system controller 231. At that time, the controller 231 stops information recording, accumulates recording information thereafter to a buffer memory 222, detects the position where the tracking is disengaged, a retracking is initiated from this position and the information accumulated in the memory 222 is recorded with a high speed. Therefore, the recording of the information is continuously performed, no loss occurs in the recorded information due to the tracking disengagement and no reusing of the optical disk is prevented.



## LEGAL STATUS

[Date of request for examination]

04.09.1995

[Date of sending the examiner's decision of rejection]

[Kind of final disposal of application other than the examiner's decision of rejection or application converted registration]

[Date of final disposal for application]

[Patent number]

2713681

[Date of registration]

31.10.1997

[Number of appeal against examiner's decision of rejection]

[Date of requesting appeal against examiner's decision of rejection]

[Date of extinction of right]

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**Japanese Patent Laid-Open Publication No. 5-282696**

Publication Date      October 29, 1993  
Application No.        4-76913  
Application Date       March 31, 1992  
Applicant              TAIYO YUDEN CO., LTD.  
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Excerpt from paragraphs 0024-0027

[0024]

According to the present embodiment, when the information to be recorded is input to the data input section 21, data of a predetermined time is accumulated in the buffer memory 22 before the information is recorded to the optical disk 1. The system controller 231 drives the spindle motor 232 to rotate the optical disk 1 at a predetermined rotating speed, and after detecting that a predetermined amount of data is accumulated in the buffer memory 222, outputs the data sequentially from the buffer memory 222 starting from the data accumulated first. The system controller 231 further starts tracking from the information recording start position by way of the tracking control circuit 237.

[0025]

The data output from the buffer memory 222 is thereby synchronized with a clock signal CK by the synchronous circuit 235, is output at a predetermined timing and converted to a recording signal by a recording correction circuit 236. A pulse laser beam is exited from the optical pick up 233 based on the recording signal and the

information is recorded onto the optical disk.

[0026]

If tracking is shifted for some reason such as, disturbance (vibration, mechanical impact), defect and the like when the information is being recorded to the optical disk 1, a tracking error signal ER is output from the tracking control circuit 237 to the system controller 231. The system controller 231, to which the tracking error signal ER is input, stops the output of the recording signal from the recording correction circuit 236 and stops the recording of information to the optical disk 1, and further, detects and stores the position at where the tracking is shifted by an absolute time information input from the signal processing circuit 234. The system controller 231 further stops data output from the buffer memory 222.

[0027]

Subsequently, the system controller 231 restarts tracking from the vicinity of the position where the tracking shifted (desirably within  $\pm 1$  EFM frame with respect to the position where the tracking shifted) through the tracking control circuit 237, and releases the output stop state of the recording signal in the recording correction circuit 236. Further, the system controller 231 outputs the accumulated data from the buffer memory 222 at a speed faster than before the tracking shifted, and increases the rotating speed of the spindle motor 232 in correspondence thereto. The information is thereby recorded at a higher speed than before the tracking is shifted.